

Linear Nested Sequents

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Natural and efficient proof systems for modal logics

Some desiderata for “good” or **natural** (sequent-style) calculi [Wansing:’02]:

- ▶ subformula property: all the material in the premisses is contained in the conclusion
- ▶ separation: distinct left and right introduction rules
- ▶ locality: no restrictions on the context
- ▶ modularity: obtain other logics by changing single rules

The desideratum of **efficiency**:

- ▶ “standard backwards proof search” is complexity-optimal (or at least not worse than for sequents)

Reminder: Normal modal logic

The **formulae** of modal logic are given by

$$A ::= \text{Var} \mid \neg A \mid A \wedge A \mid A \vee A \mid A \rightarrow A \mid \Box A$$

The **Hilbert-style presentation** of normal modal logic **K** is given by the axioms for classical propositional logic, the axiom

$$k \quad \Box(A \rightarrow B) \wedge \Box A \rightarrow \Box B$$

and the rules

$$\frac{\vdash A \quad \vdash A \rightarrow B}{\vdash B} \text{ mp} \qquad \frac{\vdash A}{\vdash \Box A} \text{ nec}$$

Sequent calculi

A **sequent** is a pair of multisets of formulae, written $\Gamma \Rightarrow \Delta$.

The standard sequent system G_K for modal logic K contains the standard propositional rules together with

$$\frac{\Gamma \Rightarrow A}{\Sigma, \Box\Gamma \Rightarrow \Box A, \Delta} \text{ k}$$

Fact

G_K is sound and cut-free complete for K and is complexity-optimal.

Subformula property:



Separation:



Locality:



(Modularity:



Efficiency:



Nested sequent calculi

Definition

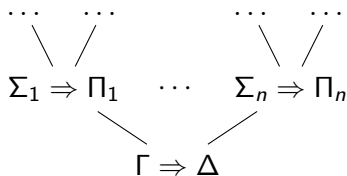
([Brünnler:'09,Poggiolesi:'09])

A **nested sequent** is a finite tree whose nodes are labelled with sequents. The **interpretation** ι of this nested sequent is

$$\wedge \Gamma \rightarrow \vee \Delta \vee \vee_{i=1}^n \Box \iota(\Sigma_i \Rightarrow \Pi_i^*).$$

Fact

The nested sequent calculus with modal rules \Box_R and \Box_L is sound and cut-free complete for modal logic K.



Nested sequent calculi

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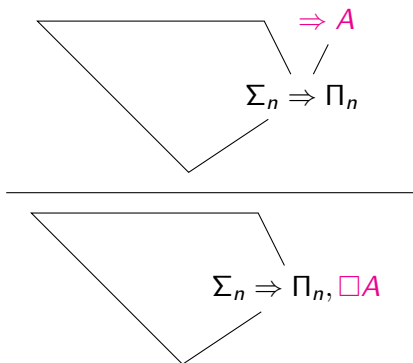
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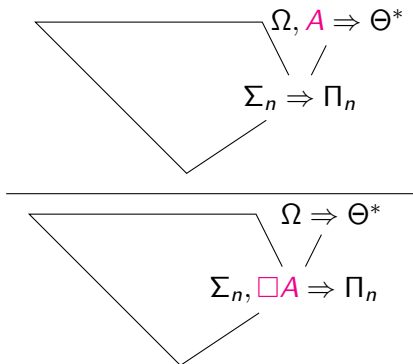
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A **nested sequent** is a finite tree whose nodes are labelled with sequents. The **interpretation** ι of this nested sequent is

$$\bigwedge \Gamma \rightarrow \bigvee \Delta \vee \bigvee_{i=1}^n \Box_{\iota}(\Sigma_i \Rightarrow \Pi_i^*) .$$

Fact

The nested sequent calculus with modal rules \Box_R and \Box_L is sound and cut-free complete for modal logic K.

Subformula property:	✓
Separation:	✓
Locality:	✓
(Modularity:	✓)
Efficiency:	✗

(Nested sequents in proof search may be of **exponential size**)

Can we combine the efficiency of sequents with the naturalness of nested sequents?

Some observations

- ▶ (Folklore) The nested sequent rules are a **step-by-step decomposition** of the standard sequent rule:

$$\frac{\Gamma \Rightarrow A}{\Box \Gamma \Rightarrow \Box A} \text{ k} \quad \rightsquigarrow \quad \frac{\frac{\frac{\Gamma \Rightarrow A}{\Box \Gamma \Rightarrow \Box A} \text{ } \Box_L}{\Rightarrow A} \text{ } \Box_R}{\Box \Gamma \Rightarrow \Box A} \text{ }$$

- ▶ Decomposing the sequent rule does not require the full tree structure of nested sequents, but only that of a **branch**.
- ▶ The data structure of a nested sequent branch is that of a **history** in backwards proof search for sequents.

Linear nested sequents

Definition

A **linear nested sequent** is a finite list of sequents, written

$$\Gamma_1 \Rightarrow \Delta_1 // \dots // \Gamma_n \Rightarrow \Delta_n$$

and interpreted as $\wedge \Gamma_1 \rightarrow \vee \Delta_1 \vee \square(\dots \square(\wedge \Gamma_n \rightarrow \vee \Delta_n) \dots)$.

The nested sequent system for K yields the modal rules of **LNS_K**:

$$\frac{\mathcal{G} // \Gamma, \square A \Rightarrow \Delta // \Sigma, A \Rightarrow \Pi}{\mathcal{G} // \Gamma, \square A \Rightarrow \Delta // \Sigma \Rightarrow \Pi} \square_L \qquad \frac{\mathcal{G} // \Gamma \Rightarrow \Delta, \square A // \Rightarrow A}{\mathcal{G} // \Gamma \Rightarrow \Delta, \square A} \square_R$$

In line with the “backwards proof search” perspective we restrict the propositional rules to the last component, e.g.:

$$\frac{\mathcal{G} // \Gamma, A, B \Rightarrow \Delta}{\mathcal{G} // \Gamma, A \wedge B \Rightarrow \Delta} \wedge_L \qquad \frac{\mathcal{G} // \Gamma \Rightarrow \Delta, A \quad \mathcal{G} // \Gamma \Rightarrow \Delta, B}{\mathcal{G} // \Gamma \Rightarrow \Delta, A \wedge B} \wedge_R$$

Linear nested sequents for K

Theorem

LNS_K is sound and complete for K and complexity-optimal.

Proof.

- ▶ Soundness: directly from the full nested sequent calculus.
- ▶ Completeness: By **simulating a sequent derivation in the last components**: (\mathcal{G} is the history)

$$\frac{\frac{\Gamma \Rightarrow A}{\Sigma, \Box \Gamma \Rightarrow \Box A, \Delta} \quad k}{\vdots \mathcal{G}} \quad \rightsquigarrow \quad \frac{\frac{\mathcal{G} // \Sigma, \Box \Gamma \Rightarrow \Box A, \Delta // \Gamma \Rightarrow A}{\mathcal{G} // \Sigma, \Box \Gamma \Rightarrow \Box A, \Delta // \Rightarrow A} \quad \Box_L}{\mathcal{G} // \Sigma, \Box \Gamma \Rightarrow \Box A, \Delta} \quad \Box_R$$

- ▶ Complexity: By noticing that LNS_K derivations are essentially sequent derivations with history. Or directly. \square

Corollary

The nested sequent calculus for K is cut-free complete.

Taking it further: monotone modal logics

The language of **monotone** modal logic **M** is that of modal logic.

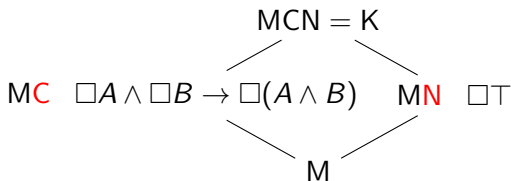
The **Hilbert-style presentation** of **M** is given by axioms and rules for classical propositional logic and the rule

$$\frac{\vdash A \rightarrow B}{\vdash \Box A \rightarrow \Box B} \text{ Mon}$$

The **sequent system** for **M** contains the standard propositional rules and the modal rule

$$\frac{A \Rightarrow B}{\Gamma, \Box A \Rightarrow \Box B, \Delta} \text{ Mon}$$

Common extensions:



Monotone linear nested sequents

To capture the sequent rule $\frac{A \Rightarrow B}{\Box A \Rightarrow \Box B}$ we use a marker \parallel for “unfinished rules”: A **monotone LNS** has the form ($n \geq 1$)

$$\Gamma_1 \Rightarrow \Delta_1 \parallel \dots \parallel \Gamma_n \Rightarrow \Delta_n$$

or $\Gamma_1 \Rightarrow \Delta_1 \parallel \dots \parallel \Gamma_n \Rightarrow \Delta_n \parallel \Gamma_{n+1} \Rightarrow \Delta_{n+1}$

Translating the sequent rule Mon yields the modal rules of LNS_M :

$$\frac{\mathcal{G} \parallel \Gamma \Rightarrow \Delta, \Box B \parallel \Rightarrow B}{\mathcal{G} \parallel \Gamma \Rightarrow \Delta, \Box B} \Box_R \qquad \frac{\mathcal{G} \parallel \Gamma, \Box A \Rightarrow \Delta \parallel \Sigma, A \Rightarrow \Pi}{\mathcal{G} \parallel \Gamma, \Box A \Rightarrow \Delta \parallel \Sigma \Rightarrow \Pi} \Box_L$$

The propositional rules cannot be applied inside \parallel .

The completeness proof for LNS_M then uses the simulation

$$\frac{\frac{A \Rightarrow B}{\Gamma, \Box A \Rightarrow \Box B, \Delta} \text{ Mon}}{\vdots \mathcal{G}} \rightsquigarrow \frac{\frac{\mathcal{G} \parallel \Gamma, \Box A \Rightarrow \Box B, \Delta \parallel A \Rightarrow B}{\mathcal{G} \parallel \Gamma, \Box A \Rightarrow \Box B, \Delta \parallel \Rightarrow B} \Box_L}{\mathcal{G} \parallel \Gamma, \Box A \Rightarrow \Box B, \Delta} \Box_R$$

Modularity for monotone modal logics

$$C \quad \Box A \wedge \Box B \rightarrow \Box(A \wedge B)$$

$$\frac{\mathcal{G} \parallel \Gamma \Rightarrow \Delta}{\mathcal{G} \parallel \Gamma \Rightarrow \Delta} \quad c$$

$$N \quad \Box \top$$

$$\frac{\mathcal{G} \parallel \Gamma \Rightarrow \Delta}{\mathcal{G} \parallel \Gamma \Rightarrow \Delta} \quad n$$

$$D_1 \quad \neg \Box \perp$$

$$\frac{\mathcal{G} \parallel \Rightarrow}{\mathcal{G}} \quad d_1$$

$$D_2 \quad \neg(\Box A \wedge \Box \neg A)$$

$$\frac{\mathcal{G} \parallel \Gamma, \Box A \Rightarrow \Delta \parallel A \Rightarrow}{\mathcal{G} \parallel \Gamma, \Box A \Rightarrow \Delta} \quad d_2$$

$$T \quad \Box A \rightarrow A$$

$$\frac{\mathcal{G} \parallel \Gamma, \Box A, A \Rightarrow \Delta}{\mathcal{G} \parallel \Gamma, \Box A \Rightarrow \Delta} \quad t$$

$$4 \quad \Box A \rightarrow \Box \Box A$$

$$\frac{\mathcal{G} \parallel \Gamma, \Box A \Rightarrow \Delta \parallel \Sigma, \Box A \Rightarrow \Pi}{\mathcal{G} \parallel \Gamma, \Box A \Rightarrow \Delta \parallel \Sigma \Rightarrow \Pi} \quad 4$$

$$5 \quad \Box \neg A \vee \Box \neg \Box A$$

$$\frac{\mathcal{G} \parallel \Gamma \Rightarrow \Delta, \Box A \parallel \Sigma \Rightarrow \Pi, \Box A}{\mathcal{G} \parallel \Gamma \Rightarrow \Delta, \Box A \parallel \Sigma \Rightarrow \Pi} \quad 5$$

Theorem

For $\mathcal{A} \subseteq \{C, N, D_1, D_2, T, 4\}$ the calculus $LNS_{M\mathcal{A}}$ is sound and complete for $M\mathcal{A}$. Similar for some combinations with 5.

(Use calculi e.g. from [Lavendhomme-Lucas:'00, Indrzejczak:'05].)

Evaluation

LNS provide efficient and natural proof systems for these logics:

Subformula property:	✓
Separation:	✓
Locality:	✓
Modularity:	✓
Efficiency:	✓

Remark 1: Similarly we get LNS calculi for many other logics, e.g.:

- ▶ simply dependent bimodal logics
- ▶ (first-order) intuitionistic logic - linking Maehara's LJ' and Fitting's nested calculus

Remark 2: LNS are (almost) the **2-sequents** from [Masini:'92]. This induces 2-sequent calculi e.g. for the normal modal logics.

Summing up

Linear nested sequents:

- ▶ a good compromise between sequents and nested sequents
- ▶ nested sequent systems for non-normal modal logics
- ▶ easy cut-free completeness proofs for nested calculi.

Bonus material

Focused labelled line sequents for K

Sequents over labelled formulae ($v : A$):

- ▶ **unfocused**: $zRx : \Gamma ; X \Rightarrow Y ; \Delta$
- ▶ **focused right**: $zR[x] : \Gamma ; X \rightarrow \cdot ; \Delta$
- ▶ **focused left**: $[x]Ry : \Gamma ; X \rightarrow Y ; \Delta$

$$\frac{zRx : \Gamma, x : B_b ; X \Rightarrow Y ; \Delta}{zRx : \Gamma ; X, x : B_b \Rightarrow Y ; \Delta} \text{str}_L \quad \frac{zRx : \Gamma ; X \Rightarrow Y ; \Delta, x : A_b}{zRx : \Gamma ; X \Rightarrow Y, x : A_b ; \Delta} \text{str}_R$$

$$\frac{}{zR[x] : \Gamma ; X, x : A \rightarrow \cdot ; \Delta, x : A} \text{init}$$

$$\frac{zR[x] : \Gamma ; X \rightarrow \cdot ; \Delta}{zRx : \Gamma ; X \Rightarrow \cdot ; \Delta} D \quad \frac{xRy : \cdot ; X \Rightarrow Y ; \Delta}{[x]Ry : \cdot ; X \rightarrow Y ; \Delta} R$$

$$\frac{[x]Ry : \Gamma ; X \rightarrow y : A ; \Delta}{zR[x] : \Gamma ; X \rightarrow \cdot ; \Delta, x : \Box A} \Box_R \quad \frac{[x]Ry : \Gamma ; X, y : A \rightarrow Y ; \Delta}{[x]Ry : \Gamma, x : \Box A ; X \rightarrow Y ; \Delta} \Box_L$$

(A_b atomic or boxed, B_b boxed)

Simply dependent bimodal logic $KT \oplus_{\subseteq} S4$

Formulae: $A ::= \text{Var} \mid \neg A \mid A \wedge A \mid A \vee A \mid A \rightarrow A \mid \Box A \mid \heartsuit A$

Axioms: Propositional axioms and rules, KT-axioms for \Box , S4-axioms for \heartsuit , and:

$$\heartsuit A \rightarrow \Box A$$

Linear nested sequent system $LNS_{KT \oplus_{\subseteq} S4}$ (with $\//^{\Box}$ and $\//^{\heartsuit}$):

$$\frac{\mathcal{G} \//^* \Gamma \Rightarrow \Delta \//^{\Box} \Rightarrow A}{\mathcal{G} \//^* \Gamma \Rightarrow \Delta, \Box A} \Box_R \quad \frac{\mathcal{G} \//^* \Gamma \Rightarrow \Delta \//^{\Box} \Sigma, A \Rightarrow \Pi}{\mathcal{G} \//^* \Gamma, \Box A \Rightarrow \Delta \//^{\Box} \Sigma \Rightarrow \Pi} \Box_L$$

$$\frac{\mathcal{G} \//^* \Gamma \Rightarrow \Delta \//^{\heartsuit} \Sigma, \heartsuit A \Rightarrow \Pi}{\mathcal{G} \//^* \Gamma, \heartsuit A \Rightarrow \Delta \//^{\heartsuit} \Sigma \Rightarrow \Pi} \heartsuit_{L\heartsuit} \quad \frac{\mathcal{G} \//^* \Gamma \Rightarrow \Delta \//^{\Box} \Sigma, \heartsuit A \Rightarrow \Pi}{\mathcal{G} \//^* \Gamma, \heartsuit A \Rightarrow \Delta \//^{\Box} \Sigma \Rightarrow \Pi} \heartsuit_{L\Box}$$

$$\frac{\mathcal{G} \//^* \Gamma \Rightarrow \Delta \//^{\heartsuit} \Rightarrow A}{\mathcal{G} \//^* \Gamma \Rightarrow \Delta, \heartsuit A} \heartsuit_R \quad \frac{\mathcal{G} \//^* \Gamma, \Box A, A \Rightarrow \Delta}{\mathcal{G} \//^* \Gamma, \Box A \Rightarrow \Delta} t_{\Box} \quad \frac{\mathcal{G} \//^* \Gamma, \heartsuit A, A \Rightarrow \Delta}{\mathcal{G} \//^* \Gamma, \heartsuit A \Rightarrow \Delta} t_{\heartsuit}$$

Intuitionistic logic

The same idea connects Maehara's multi-succedent calculus and Fitting's nested sequent calculus for first-order intuitionistic logic:

The **intuitionistic interpretation** of $\Gamma_1 \Rightarrow \Delta_1 // \dots // \Gamma_n \Rightarrow \Delta_n$ is

$$\bigwedge \Gamma_1 \rightarrow \bigvee \Delta_1 \vee (\bigwedge \Gamma_2 \rightarrow \bigvee \Delta_2 \vee (\dots (\bigwedge \Gamma_n \rightarrow \bigvee \Delta_n) \dots))$$

Restricting the nested sequent rules yields the rules of **LNS_{Int}**, e.g.:

$$\frac{\mathcal{G} // \Gamma, B \Rightarrow \Delta // \mathcal{H} \quad \mathcal{G} // \Gamma \Rightarrow \Delta, A // \mathcal{H}}{\mathcal{G} // \Gamma, A \rightarrow B \Rightarrow \Delta // \mathcal{H}} \rightarrow_L \quad \frac{\mathcal{G} // \Gamma \Rightarrow \Delta // A \Rightarrow B}{\mathcal{G} // \Gamma \Rightarrow \Delta, A \rightarrow B} \rightarrow_R$$

$$\frac{\mathcal{G} // \Gamma, A\alpha \Rightarrow \Delta // \mathcal{H}}{\mathcal{G} // \Gamma, \forall x.Ax \Rightarrow \Delta // \mathcal{H}} \forall_L \quad \frac{\mathcal{G} // \Gamma \Rightarrow \Delta // \Rightarrow A\alpha}{\mathcal{G} // \Gamma \Rightarrow \Delta, \forall x.Ax} \forall_R$$

if α in \mathcal{H} then α in $\mathcal{G} // \Gamma \Rightarrow \Delta$ α not in the conclusion

$$\frac{\mathcal{G} // \Gamma \Rightarrow \Delta // \Sigma, A \Rightarrow \Pi // \mathcal{H}}{\mathcal{G} // \Gamma, A \Rightarrow \Delta // \Sigma \Rightarrow \Pi // \mathcal{H}} \text{Lift}$$

(Rules for \exists analogous and other rules local.)

Intuitionistic logic: Completeness

We simulate Maehara's rules in the last components, e.g.:

$$\frac{\Gamma, A \Rightarrow B}{\Gamma \Rightarrow \Delta, A \rightarrow B} \rightarrow_R \quad \rightsquigarrow \quad \frac{\mathcal{G} // \Gamma \Rightarrow \Delta, A \rightarrow B // \Gamma, A \Rightarrow B}{\mathcal{G} // \Gamma \Rightarrow \Delta, A \rightarrow B // A \Rightarrow B} \text{Lift} \rightarrow_R$$

$\vdots \mathcal{G}$

$$\frac{\Gamma \Rightarrow A\alpha}{\Gamma \Rightarrow \Delta, \forall x.Ax} \forall_R \quad \rightsquigarrow \quad \frac{\mathcal{G} // \Gamma \Rightarrow \Delta, \forall x.Ax // \Gamma \Rightarrow A\alpha}{\mathcal{G} // \Gamma \Rightarrow \Delta, \forall x.Ax // \Rightarrow A\alpha} \text{Lift} \forall_R$$

$\vdots \mathcal{G}$

The other rules are easy.

Theorem

LNS_{Int} is sound and complete for first-order intuitionistic logic.

Corollary: Cut-free completeness of Fitting's calculus.

Hypersequents

The data structure of LNS is rather familiar from another setting:

Definition ([Avron:'96])

A **hypersequent** is a finite list of sequents, written

$$\Gamma_1 \Rightarrow \Delta_1 \mid \cdots \mid \Gamma_n \Rightarrow \Delta_n$$

and interpreted as $\Box(\wedge \Gamma_1 \rightarrow \vee \Delta_1) \vee \cdots \vee \Box(\wedge \Gamma_n \rightarrow \vee \Delta_n)$.

This interpretation suggests the **external structural rules**:

$$\frac{\mathcal{G} \mid \Sigma \Rightarrow \Pi \mid \Gamma \Rightarrow \Delta \mid \mathcal{H}}{\mathcal{G} \mid \Gamma \Rightarrow \Delta \mid \Sigma \Rightarrow \Pi \mid \mathcal{H}} \text{EEX}$$

$$\frac{\mathcal{G} \mid \Gamma \Rightarrow \Delta \mid \Gamma \Rightarrow \Delta \mid \mathcal{H}}{\mathcal{G} \mid \Gamma \Rightarrow \Delta \mid \mathcal{H}} \text{EC}$$

$$\frac{\mathcal{G} \mid \mathcal{H}}{\mathcal{G} \mid \Gamma \Rightarrow \Delta \mid \mathcal{H}} \text{EW}$$

They are part of almost all hypersequent calculi for modal logics.

Hypersequents and linear nested sequents

Observation 1: EC and EW are the **structural nested sequent rules** for (4) and (t) (modulo internal structural rules):

$$\frac{\mathcal{G} \mid \Gamma \Rightarrow \Delta \mid \Gamma \Rightarrow \Delta \mid \mathcal{H}}{\mathcal{G} \mid \Gamma \Rightarrow \Delta \mid \mathcal{H}} \text{ EC} \quad \text{vs.} \quad \frac{\mathcal{G} \parallel \Gamma \Rightarrow \Delta \parallel \Sigma \Rightarrow \Pi \parallel \mathcal{H}}{\mathcal{G} \parallel \Gamma, \Sigma \Rightarrow \Delta, \Pi \parallel \mathcal{H}} \dot{t}$$

$$\frac{\mathcal{G} \mid \mathcal{H}}{\mathcal{G} \mid \Gamma \Rightarrow \Delta \mid \mathcal{H}} \text{ EW} \quad \text{vs.} \quad \frac{\mathcal{G} \parallel \mathcal{H}}{\mathcal{G} \parallel \Rightarrow \parallel \mathcal{H}} \bar{4}$$

Observation 2: $\text{LNS}_K + \dot{t} + \bar{4} + \text{EEX}$ is (essentially) the hypersequent calculus for S5 from [Restall:'07].

Theorem

$\text{LNS}_K + \dot{t} + \bar{4} + \text{EEX}$ is sound and cut-free complete for S5 (under the LNS-interpretation).

(Similarly we obtain e.g. Avron's calculus etc.)