

From Hypersequents to Parallel Processes

Francesco A. Genco¹
(joint work with Agata Ciabattoni
and partly with Federico Aschieri)

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Proof theory of non-classical logics

Analytic and modular calculi for classes of logics

- Proof search
- Prove meta-logical properties in a constructive way

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A jungle of formalisms

(sequents, hypersequents, labelled sequents,
nested sequents, display calculus, calculus of structures...)

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Embeddings

- Expressiveness relations between formalisms
- Transfer of results (avoiding repetitions and mistakes)

[Wansing, 1998], [Fitting, 2012],
[Goré and Ramanayake, 2012], [Ramanayake 2015, 2016]...

Sequent calculus [Gentzen, 1935]

$$\Gamma \Rightarrow \Delta$$

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Some sequent rules:

$$\frac{\Gamma, A, B \Rightarrow \Delta}{\Gamma, A \wedge B \Rightarrow \Delta} (l\wedge)$$

$$\frac{\Gamma \Rightarrow A \quad \Gamma, A \Rightarrow \Delta}{\Gamma \Rightarrow \Delta} (cut)$$

$$\frac{\Gamma \Rightarrow \Delta}{\Gamma, A \Rightarrow \Delta} (lw)$$

The method of structural rules

To obtain analytic and modular calculi

- Fix an analytic base calculus
- Define a translation from axioms to (analyticity-preserving) rules
- Obtain a **general systematic framework**

Large classes of logics captured

[Ciabattoni et al., 2008]

[<https://www.logic.at/tinc/webaxiomcalc/>]

Beyond sequents

Sequents are **simple** and **versatile**

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Sequents are **simple** and **versatile**

but **not enough** to define modular analytic proof systems **for many interesting logics**

Consider the axioms for **intermediate logics**:

$$\left\{ \begin{array}{ll} \neg\neg A \vee \neg A & \text{Jankov} \\ (A \rightarrow B) \vee (B \rightarrow A) & \text{Gödel} \\ A \vee (A \rightarrow (B \vee (B \rightarrow C))) & \text{Bd}_2 \\ \vdots & \end{array} \right.$$

No sequent structural rule can capture these axioms
[Ciabattoni et al., 2012, Ann. Pure Appl. Logic]

More structure

The *linearity axiom* characterises *Gödel logic*

$$(A \rightarrow B) \vee (B \rightarrow A)$$

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The *linearity axiom* characterises *Gödel logic*

$$(A \rightarrow B) \vee (B \rightarrow A)$$

We can define structural rules based on the syntax of this axiom using two (simple) generalisations of sequents:

HYPERSEQUENTS

[Mints, 1968]

[Pottinger, 1983]

[Avron, 1987]

and

SYSTEMS OF RULES

[Negri, 2014]

Hypersequents [Mints, 1968], [Pottinger, 1983], [Avron, 1987]

Multiset of sequents (interpreted disjunctively)

$$\Gamma_1 \Rightarrow \Delta_1 \mid \dots \mid \Gamma_n \Rightarrow \Delta_n$$

Hypersequents [Mints, 1968], [Pottinger, 1983], [Avron, 1987]

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$$\Gamma_1 \Rightarrow \Delta_1 \mid \dots \mid \Gamma_n \Rightarrow \Delta_n$$

We can represent the *linearity axiom* as

$$(A \rightarrow B) \vee (B \rightarrow A)$$

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$$\Gamma_1 \Rightarrow \Delta_1 \mid \dots \mid \Gamma_n \Rightarrow \Delta_n$$

We can represent the *linearity axiom* as

$$\Rightarrow A \rightarrow B \mid \Rightarrow B \rightarrow A$$

Hypersequents [Mints, 1968], [Pottinger, 1983], [Avron, 1987]

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Multiset of sequents (interpreted disjunctively)

$$\Gamma_1 \Rightarrow \Delta_1 \mid \dots \mid \Gamma_n \Rightarrow \Delta_n$$

We can represent the *linearity axiom* as

$$A \Rightarrow B \mid B \Rightarrow A$$

and transform this into the rule

$$\frac{\mathcal{G} \mid B, \Gamma_1 \Rightarrow \Delta_1 \quad \mathcal{G} \mid A, \Gamma_2 \Rightarrow \Delta_2}{\mathcal{G} \mid A, \Gamma_1 \Rightarrow \Delta_1 \mid B, \Gamma_2 \Rightarrow \Delta_2}$$

Example of hypersequent derivation

$$\frac{\mathcal{G} \mid B, \Gamma_1 \Rightarrow \Delta_1 \quad \mathcal{G} \mid A, \Gamma_2 \Rightarrow \Delta_2}{\mathcal{G} \mid A, \Gamma_1 \Rightarrow \Delta_1 \mid B, \Gamma_2 \Rightarrow \Delta_2} \text{ (com)} \quad \frac{\mathcal{G} \mid \Gamma \Rightarrow \Delta \mid \Gamma \Rightarrow \Delta}{\mathcal{G} \mid \Gamma \Rightarrow \Delta} \text{ (EC)}$$

$$\frac{\frac{\frac{\frac{\overline{B \Rightarrow B} \text{ init.}}{A \Rightarrow B \mid B \Rightarrow A} \text{ (com)}}{A \Rightarrow B \mid \Rightarrow B \rightarrow A} (\rightarrow r)}{\Rightarrow A \rightarrow B \mid \Rightarrow B \rightarrow A} (\rightarrow r)}{\Rightarrow A \rightarrow B \mid \Rightarrow (A \rightarrow B) \vee (B \rightarrow A)} (\vee r)}{\Rightarrow (A \rightarrow B) \vee (B \rightarrow A) \mid \Rightarrow (A \rightarrow B) \vee (B \rightarrow A)} (\vee r)}{\Rightarrow (A \rightarrow B) \vee (B \rightarrow A)} \text{ (EC)}$$

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Systems of rules [Negri, 2014, J. Logic Comput]

Set of rules with:

- order constraints
- shared formula meta-variables

Very expressive formalism

Systems of rules on labelled sequents (*e.g.*, “ $xRy, \Gamma \Rightarrow \Delta, y : A$ ”) capture all normal modal logics formalised by Sahlqvist formulae

Systems of rules

Set of rules with:

- order constraints
- shared formula meta-variables

We will consider
purely syntactical two-level systems:

$$\frac{\frac{\Gamma_1^1 \Rightarrow \Delta_1^1 \dots \Gamma_1^{n_1} \Rightarrow \Delta_1^{n_1}}{\Gamma_1 \Rightarrow \Delta_1} (top_1) \quad \dots \quad \frac{\Gamma_k^1 \Rightarrow \Delta_k^1 \dots \Gamma_k^{n_k} \Rightarrow \Delta_k^{n_k}}{\Gamma_k \Rightarrow \Delta_k} (top_k)}{\Gamma \Rightarrow \Delta} (bottom)$$

Example of system

We represent the axiom $(A \rightarrow B) \vee (B \rightarrow A)$ as the system

$$\frac{\frac{B, \Gamma_1 \Rightarrow \Delta_1}{A, \Gamma_1 \Rightarrow \Delta_1} (com_1) \quad \frac{A, \Gamma_2 \Rightarrow \Delta_2}{B, \Gamma_2 \Rightarrow \Delta_2} (com_2)}{\frac{\Gamma \Rightarrow \Delta}{\Gamma \Rightarrow \Delta} (ec)}$$

Example of system of rules derivation

$$\begin{array}{c}
 \frac{B, \Gamma_1 \Rightarrow \Delta_1}{A, \Gamma_1 \Rightarrow \Delta_1} \text{ (com}_1\text{)} \\
 \vdots \\
 \Gamma \Rightarrow \Delta
 \end{array}
 \quad
 \begin{array}{c}
 \frac{A, \Gamma_2 \Rightarrow \Delta_2}{B, \Gamma_2 \Rightarrow \Delta_2} \text{ (com}_1\text{)} \\
 \vdots \\
 \Gamma \Rightarrow \Delta \text{ (ec)}
 \end{array}
 \quad
 \frac{\Gamma \Rightarrow \Delta}{\Gamma \Rightarrow \Delta}$$

$$\begin{array}{c}
 \frac{\overline{B \Rightarrow B} \text{ init.}}{A \Rightarrow B} \text{ (com}_1\text{)} \\
 \frac{A \Rightarrow B}{\Rightarrow A \rightarrow B} \text{ (}\rightarrow r\text{)} \\
 \frac{\Rightarrow A \rightarrow B}{\Rightarrow (A \rightarrow B) \vee (B \rightarrow A)} \text{ (}\vee r\text{)}
 \end{array}
 \quad
 \begin{array}{c}
 \frac{\overline{A \Rightarrow A} \text{ init.}}{B \Rightarrow A} \text{ (com}_2\text{)} \\
 \frac{B \Rightarrow A}{\Rightarrow B \rightarrow A} \text{ (}\rightarrow r\text{)} \\
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A casual resemblance?

$$\frac{\mathcal{G} \mid B, \Gamma_1 \Rightarrow \Delta_1 \quad \mathcal{G} \mid A, \Gamma_2 \Rightarrow \Delta_2}{\mathcal{G} \mid A, \Gamma_1 \Rightarrow \Delta_1 \mid B, \Gamma_2 \Rightarrow \Delta_2}$$
$$\frac{\frac{B, \Gamma_1 \Rightarrow \Delta_1}{A, \Gamma_1 \Rightarrow \Delta_1} \quad \frac{A, \Gamma_2 \Rightarrow \Delta_2}{B, \Gamma_2 \Rightarrow \Delta_2}}{\Gamma \Rightarrow \Delta} \Gamma \Rightarrow \Delta$$

The two formalisms seem to be related

Can we formalise this intuition in its full generality?

Where does this lead to?

The Embedding

[Ciabattoni and Genco. Journal version in preparation.]

Rule translation

- Any hypersequent rule can be rewritten as a two-level system of rules
- Any two-level system of rules can be rewritten as a hypersequent rule

$$\frac{\mathcal{G} \mid \Gamma'_1 \Rightarrow \Delta'_1 \quad \dots \quad \mathcal{G} \mid \Gamma'_k \Rightarrow \Delta'_k}{\mathcal{G} \mid \Gamma_1 \Rightarrow \Delta_1 \mid \dots \mid \Gamma_n \Rightarrow \Delta_n}$$

$\mathcal{S}_1, \dots, \mathcal{S}_n$ sets of sequents $\Downarrow \mathcal{S}_1 \cup \dots \cup \mathcal{S}_n = \{\Gamma'_i \Rightarrow \Delta'_i\}_{1 \leq i \leq k}$

$$\frac{\frac{\mathcal{S}_1}{\Gamma_1 \Rightarrow \Delta_1} \quad \dots \quad \frac{\mathcal{S}_n}{\Gamma_n \Rightarrow \Delta_n}}{\Gamma \Rightarrow \Delta}$$

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$$\frac{\frac{\mathcal{S}_1}{\Gamma_1 \Rightarrow \Delta_1} \quad \dots \quad \frac{\mathcal{S}_n}{\Gamma_n \Rightarrow \Delta_n}}{\Gamma \Rightarrow \Delta}$$

Derivation translation

Any hypersequent derivation can be translated into a two-level systems derivation using corresponding rules, and vice versa

- Individual translations are quite simple and natural
- The order of rule applications is preserved
- The general proof, on the other hand, is complex:
 - non-locality of systems of rules
 - general form of rules

Example of derivation translation

$$\begin{array}{c}
 \frac{A \Rightarrow A}{A \Rightarrow A \mid B \Rightarrow A \wedge B} \text{ (EW)} \quad \frac{\frac{B \Rightarrow B \quad A \Rightarrow A}{A \Rightarrow B \mid B \Rightarrow A} \text{ (com)} \quad \frac{B \Rightarrow B}{A \Rightarrow B \mid B \Rightarrow B} \text{ (EW)}}{A \Rightarrow B \mid B \Rightarrow A \wedge B} \text{ (\wedge r)} \\
 \hline
 \frac{A \Rightarrow A \wedge B \mid B \Rightarrow A \wedge B}{A \Rightarrow A \wedge B \mid \Rightarrow B \rightarrow (A \wedge B)} \text{ (\wedge r)} \\
 \frac{A \Rightarrow A \wedge B \mid \Rightarrow B \rightarrow (A \wedge B)}{\Rightarrow A \rightarrow (A \wedge B) \mid \Rightarrow B \rightarrow (A \wedge B)} \text{ (\rightarrow r)} \\
 \hline
 \frac{\Rightarrow A \rightarrow (A \wedge B) \mid \Rightarrow B \rightarrow (A \wedge B)}{\Rightarrow A \rightarrow (A \wedge B) \mid \Rightarrow (A \rightarrow (A \wedge B)) \vee (B \rightarrow (A \wedge B))} \text{ (\vee r)} \\
 \hline
 \frac{\Rightarrow (A \rightarrow (A \wedge B)) \vee (B \rightarrow (A \wedge B)) \mid \Rightarrow (A \rightarrow (A \wedge B)) \vee (B \rightarrow (A \wedge B))}{\Rightarrow (A \rightarrow (A \wedge B)) \vee (B \rightarrow (A \wedge B))} \text{ (EC)}
 \end{array}$$

⇕

$$\begin{array}{c}
 \frac{A \Rightarrow A \quad \frac{B \Rightarrow B}{A \Rightarrow B} \text{ (com}_1\text{)}}{A \Rightarrow A \wedge B} \text{ (\wedge r)} \\
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How far does this go?

The two formalisms are equivalent
w.r.t. intermediate logics

Nonetheless, the embedding does not depend
on the logical rules in an essential way

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on the logical rules in an essential way



It can be naturally extended to other calculi
(*e.g.*, the hypersequent calculi for modal logics
in [Kurokawa, 2013][Lahav, 2013][Indrzejczak, 2015])

Applications of the Embedding

Systems of rules made local

By the embedding we can
represent any two-level system of rules in a local form:

$$\frac{\frac{B, \Gamma_1 \Rightarrow \Delta_1}{A, \Gamma_1 \Rightarrow \Delta_1} \quad \frac{A, \Gamma_2 \Rightarrow \Delta_2}{B, \Gamma_2 \Rightarrow \Delta_2}}{\frac{\Gamma \Rightarrow \Delta \quad \Gamma \Rightarrow \Delta}{\Gamma \Rightarrow \Delta}} \quad \rightsquigarrow \quad \frac{\mathcal{G} \mid B, \Gamma_1 \Rightarrow \Delta_1 \quad \mathcal{G} \mid A, \Gamma_2 \Rightarrow \Delta_2}{\mathcal{G} \mid A, \Gamma_1 \Rightarrow \Delta_1 \mid B, \Gamma_2 \Rightarrow \Delta_2}$$

Systems of rules made analytic

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To obtain an **analytic 2-level system of rules**

Hypersequents made natural

The embedding provides a connection
between hypersequents and N.D. as well

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$$\frac{B, \Gamma_1 \Rightarrow \Delta_1 \quad A, \Gamma_2 \Rightarrow \Delta_2}{A, \Gamma_1 \Rightarrow \Delta_1 \mid B, \Gamma_2 \Rightarrow \Delta_2} \xrightarrow{\text{embedding}} \frac{\frac{B, \Gamma_1 \Rightarrow \Delta_1}{A, \Gamma_1 \Rightarrow \Delta_1} \quad \frac{A, \Gamma_2 \Rightarrow \Delta_2}{B, \Gamma_2 \Rightarrow \Delta_2}}{\Gamma \Rightarrow \Delta}$$

\vdots

$$\frac{\frac{A}{B} \quad \frac{B}{A}}{F}$$

\vdots

$$\frac{F \quad F}{F}$$

The Computational Meaning

The computational meaning of hypersequents

[Avron, 1991]

Intermediate logics formalised by **hypersequent calculi**
could serve as base for **parallel λ -calculi**

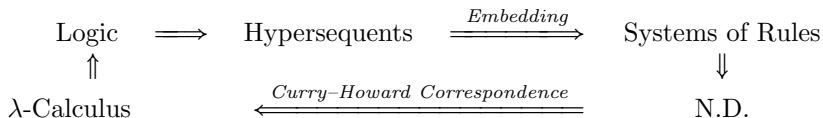
The computational meaning of hypersequents

[Avron, 1991]

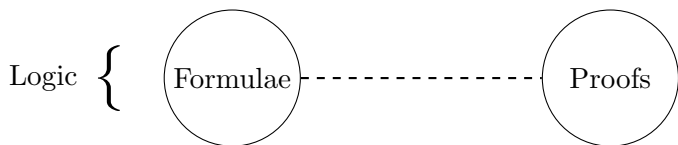
Intermediate logics formalised by **hypersequent calculi**
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The Problem

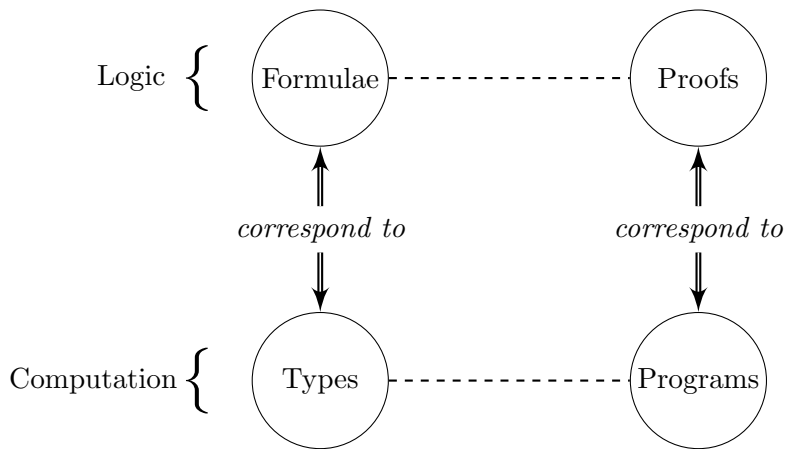
Find **computational interpretations** for these logics



The Curry–Howard correspondence [Howard, 1980]



The Curry–Howard correspondence [Howard, 1980]



The implication rules, for example

$$\frac{t : A \rightarrow B \quad u : A}{tu : B}$$

$$\frac{\begin{array}{c} [x : A] \\ \vdots \\ t : B \end{array}}{\lambda x. t : A \rightarrow B}$$

Moving to Gödel logic

The linearity rule

$$\frac{\frac{A}{B} \quad \dots \quad F \quad \frac{B}{A} \quad \dots \quad F}{F}$$

Moving to Gödel logic

The linearity rule

$$\frac{\frac{u : A}{eu : B} \quad \vdots \quad s : F \quad \frac{v : B}{ev : A} \quad \vdots \quad t : F}{F} F$$

Moving to Gödel logic

The linearity rule

$$\frac{\frac{u:A}{eu:B} \quad \vdots \quad s:F \quad \frac{v:B}{ev:A} \quad \vdots \quad t:F}{s \parallel_e t:F}$$

Moving to Gödel logic

The linearity rule

$$\frac{\frac{[e : A \rightarrow B] \quad u : A}{eu : B} \quad \frac{[e : B \rightarrow A] \quad v : B}{ev : A}}{\frac{s : F \quad t : F}{s \parallel_e t : F}}$$

A derivation, a program

$$\begin{array}{c}
 \frac{[x : ((A \rightarrow B) \rightarrow F) \wedge ((B \rightarrow A) \rightarrow F)]^1}{\pi_1 x : (B \rightarrow A) \rightarrow F} \quad \frac{[e : B \rightarrow A]^2}{(\pi_1 x)e : F} \\
 \vdots \\
 \frac{[x : ((A \rightarrow B) \rightarrow F) \wedge ((B \rightarrow A) \rightarrow F)]^1}{\pi_0 x : (A \rightarrow B) \rightarrow F} \quad \frac{[e : A \rightarrow B]^2}{(\pi_0 x)e : F} \quad \frac{(\pi_1 x)e : F}{2} \\
 \frac{(\pi_0 x)e \parallel_e (\pi_1 x)e : F}{\lambda x. (\pi_0 x)e \parallel_e (\pi_1 x)e : ((A \rightarrow B) \rightarrow F) \wedge ((B \rightarrow A) \rightarrow F) \rightarrow F} \quad 1
 \end{array}$$

A derivation, a program

$$\begin{array}{c}
 \frac{[x : ((A \rightarrow B) \rightarrow F) \wedge ((B \rightarrow A) \rightarrow F)]^1}{\pi_1 x : (B \rightarrow A) \rightarrow F} \quad \frac{[e : B \rightarrow A]^2}{(\pi_1 x)e : F} \\
 \vdots \\
 \frac{[x : ((A \rightarrow B) \rightarrow F) \wedge ((B \rightarrow A) \rightarrow F)]^1}{\pi_0 x : (A \rightarrow B) \rightarrow F} \quad \frac{[e : A \rightarrow B]^2}{(\pi_0 x)e : F} \quad \frac{(\pi_1 x)e : F}{2} \\
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A derivation, a program

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 \hline
 (\pi_1 x)e : F \\
 \vdots \\
 \vdots \\
 \vdots \\
 \frac{[x : ((A \rightarrow B) \rightarrow F) \wedge ((B \rightarrow A) \rightarrow F)]^1}{\pi_0 x : (A \rightarrow B) \rightarrow F} \quad [e : A \rightarrow B]^2 \\
 \hline
 (\pi_0 x)e : F \quad (\pi_1 x)e : F \quad 2 \\
 \hline
 (\pi_0 x)e \parallel_e (\pi_1 x)e : F \\
 \hline
 \lambda x. (\pi_0 x)e \parallel_e (\pi_1 x)e : ((A \rightarrow B) \rightarrow F) \wedge ((B \rightarrow A) \rightarrow F) \rightarrow F \quad 1
 \end{array}$$

A derivation, a program

$$\begin{array}{c}
 \frac{[x : ((A \rightarrow B) \rightarrow F) \wedge ((B \rightarrow A) \rightarrow F)]^1}{\pi_1 x : (B \rightarrow A) \rightarrow F} \quad \frac{[e : B \rightarrow A]^2}{(\pi_1 x)e : F} \\
 \vdots \\
 \frac{[x : ((A \rightarrow B) \rightarrow F) \wedge ((B \rightarrow A) \rightarrow F)]^1}{\pi_0 x : (A \rightarrow B) \rightarrow F} \quad \frac{[e : A \rightarrow B]^2}{(\pi_0 x)e : F} \quad \vdots \\
 \frac{(\pi_0 x)e : F \quad (\pi_1 x)e : F}{(\pi_0 x)e \parallel_e (\pi_1 x)e : F} \quad 2 \\
 \frac{(\pi_0 x)e \parallel_e (\pi_1 x)e : F}{\lambda x. (\pi_0 x)e \parallel_e (\pi_1 x)e : ((A \rightarrow B) \rightarrow F) \wedge ((B \rightarrow A) \rightarrow F) \rightarrow F} \quad 1
 \end{array}$$

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 \end{array}$$

Normalisation, computation

Normalisation procedure

- removing detours
- subformula property

Proof transformation steps



Steps of the **computation**

Implication reduction, for example

$$\frac{\frac{\Gamma_0, [x : A]^1 \quad \vdots \quad u : B}{\lambda x. u : A \rightarrow B} \quad 1 \quad \frac{\Gamma_1 \quad \mathcal{P}}{t : A}}{(\lambda x. u)t : B} \quad \mapsto \quad \frac{\Gamma_1 \quad \mathcal{P}}{\Gamma_0, t : A} \quad \vdots \quad u[t/x] : B$$

Cross reductions

$$\mathcal{C}[eu] \parallel_e \mathcal{D}[ev]$$

$$\frac{\begin{array}{c} \Gamma \\ \mathcal{P}_1 \\ \frac{A}{B} \\ \vdots \\ F \end{array} \quad \begin{array}{c} \Delta \\ \mathcal{P}_2 \\ \frac{B}{A} \\ \vdots \\ F \end{array}}{F} e$$

Cross reductions

$$\mathcal{C}[eu] \parallel_e \mathcal{D}[ev]$$

$$\mathcal{D}[u^{e'\langle \bar{z} \rangle / \bar{y}}]$$

$$\mathcal{C}[v^{e'\langle \bar{y} \rangle / \bar{z}}]$$

Γ	Δ	$\frac{\Delta}{\Gamma}$	$\frac{\Gamma}{\Delta}$
\mathcal{P}_1	\mathcal{P}_2	\mathcal{P}_1	\mathcal{P}_2
$\frac{A}{B}$	$\frac{B}{A}$	A	B
\vdots	\vdots	\vdots	\vdots
F	F	F	F
$\frac{F}{F}$	e	F	e'

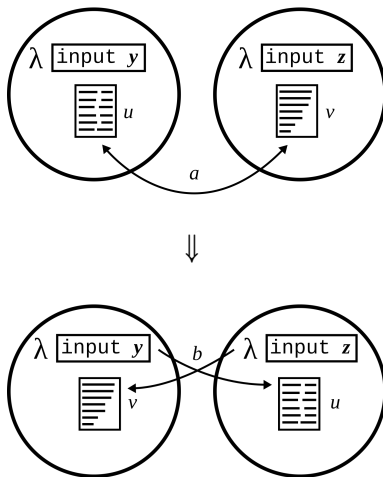
Cross reductions

$$\mathcal{C}[eu] \parallel_e \mathcal{D}[ev] \quad \mapsto$$

$$(\mathcal{D}[u^{e'\langle \bar{z} \rangle / \bar{y}}] \parallel_e \mathcal{C}[eu]) \parallel_{e'} (\mathcal{C}[v^{e'\langle \bar{y} \rangle / \bar{z}}] \parallel_e \mathcal{D}[ev])$$

$$\begin{array}{ccc}
 \begin{array}{cc}
 \Gamma & \Delta \\
 \mathcal{P}_1 & \mathcal{P}_2 \\
 \frac{A}{B} & \frac{B}{A} \\
 \vdots & \vdots \\
 \frac{F}{F} & \frac{F}{F} \\
 \hline
 F & F \\
 \hline
 & e
 \end{array} & \mapsto &
 \begin{array}{cc}
 \frac{\Delta}{\Gamma} & \Gamma \\
 \mathcal{P}_1 & \mathcal{P}_1 \\
 \frac{A}{B} & \frac{A}{B} \\
 \vdots & \vdots \\
 \frac{F}{F} & \frac{F}{F} \\
 \hline
 F & F \\
 \hline
 & e
 \end{array}
 \end{array}
 \quad \mapsto \quad
 \begin{array}{cc}
 \frac{\Gamma}{\Delta} & \Delta \\
 \mathcal{P}_2 & \mathcal{P}_2 \\
 \frac{B}{A} & \frac{B}{A} \\
 \vdots & \vdots \\
 \frac{F}{F} & \frac{F}{F} \\
 \hline
 F & F \\
 \hline
 & e
 \end{array}$$

Communications



Curry–Howard correspondence for propositional Gödel logic

[Aschieri, Ciabattoni and Genco. Submitted.]

- Normalisation
- Subformula property
- Meaningful computational reductions
(*e.g.*, in terms of optimisation via code mobility)

Future work

Find other **computational interpretations** of logics
formalised by hypersequent calculi

$$x^A : A \quad \frac{[x^A : A] \quad \vdots \quad u : B}{\lambda x^A u : A \rightarrow B} \quad \frac{t : A \rightarrow B \quad u : A}{tu : B}$$

$$\frac{u : A \quad t : B}{\langle u, t \rangle : A \wedge B}$$

$$\frac{u : A \wedge B}{u \pi_0 : A}$$

$$\frac{u : A \wedge B}{u \pi_1 : B}$$

$$[a^{A \rightarrow B} : A \rightarrow B]$$

$$[a^{B \rightarrow A} : B \rightarrow A]$$

$$\vdots$$

$$\vdots$$





$$u : C$$





$$v : C$$





$$\frac{u : C \quad v : C}{u \parallel_a v : C}$$





$$\frac{\Gamma \vdash u : \perp}{\Gamma \vdash \text{efq}_P(u) : P}$$


with P atomic, $P \neq \perp$.

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